

Soft-error Sensitivity of Distributed Deep Learning

14th International SuperComputing Camp 2023



Esteban Meneses, PhD

Advanced Computing Laboratory
Costa Rica National High Technology Center
emeneses@cenat.ac.cr



Where do I come from?

Costa Rica, Central America



is not Puerto Rico
has no standing army since 1949
hosts 6% of world's biodiversity
produces 99% of its electricity from renewable sources

Soft-error
Sensitivity of
Distributed Deep
Learning

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Motivation

Distributed Deep
Learning

Deep Learning Models
Distributed Computing

Checkpoint
Alteration

Design
Implementation
Results

Soft-error
Sensitivity

Experimental Setup
Experimental Results

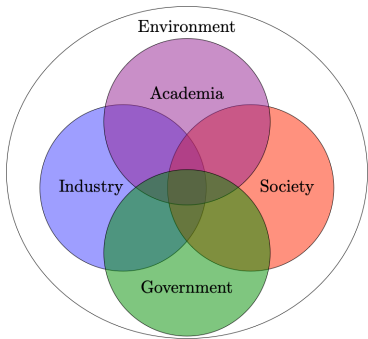
Conclusion

CeNAT-CONARE Campus, San José, Costa Rica



Costa Rica National High Technology Center

CeNAT



Development through Knowledge

Advanced Computing Laboratory

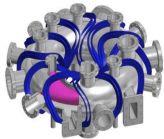
Powered by a computing-centered diverse team



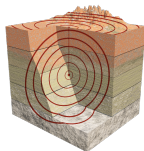
Collaborative Research Projects

Accelerating scientific discovery

Energy



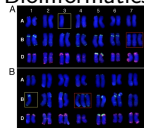
Seismology



Biodiversity



Bioinformatics



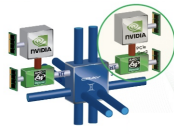
Climate



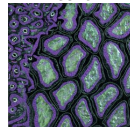
Epidemics



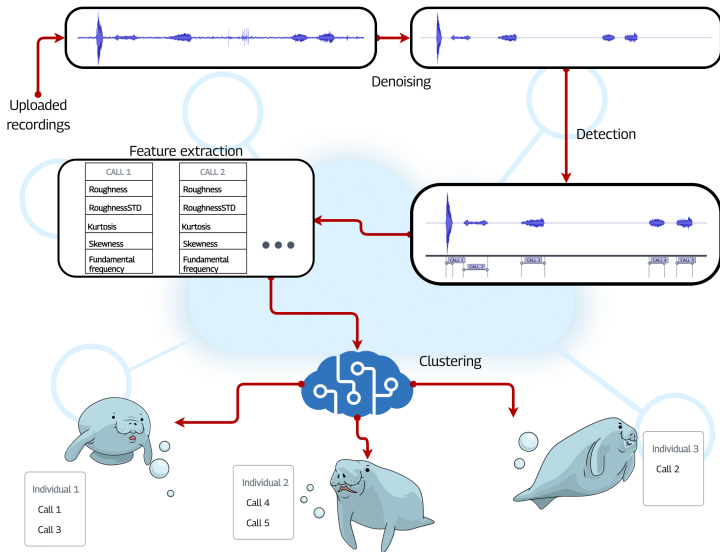
HPC

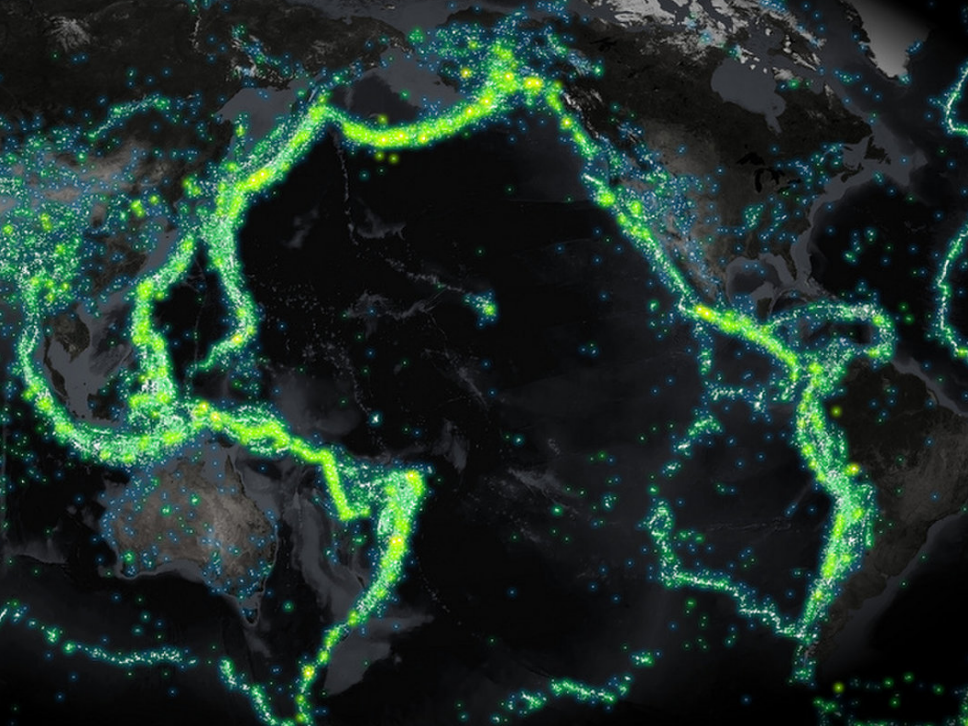


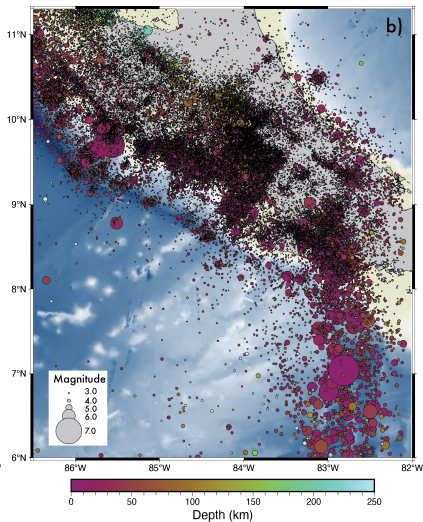
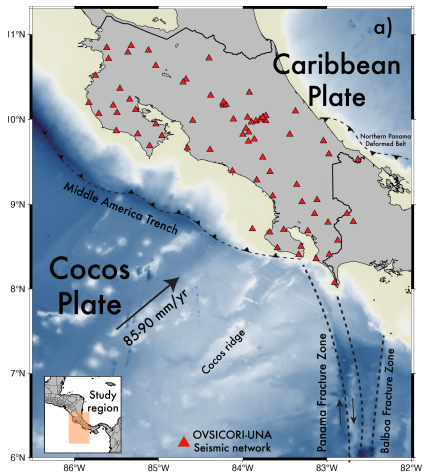
Health











Supercomputing Infrastructure

Simulation + Data Science + Artificial Intelligence + Bioinformatics



Advanced Computing Training

Empowering collaborators

Programming



Scientific Computing



Machine Learning



System Tutorial



Programming



Data Visualization



Statistical Analysis



Bioinformatics



HPC SCHOOL
— COSTA RICA —



Costa Rica HPC School, January, 2023

Outline

Motivation

Distributed Deep Learning

- Deep Learning Models
- Distributed Computing

Checkpoint Alteration

- Design
- Implementation
- Results

Soft-error Sensitivity

- Experimental Setup
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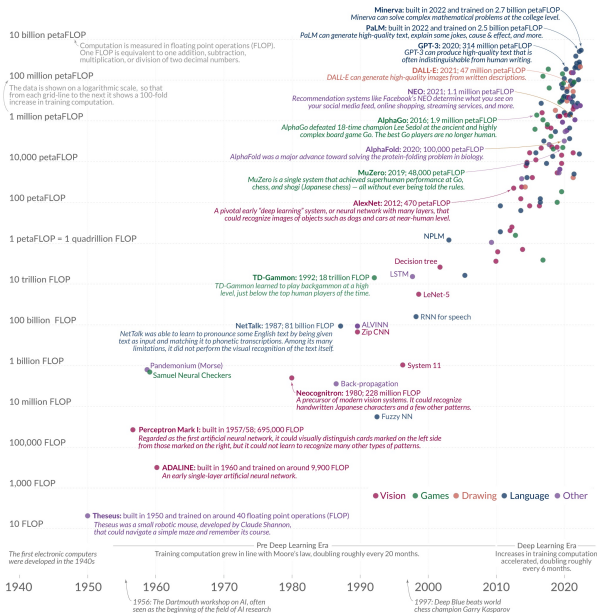
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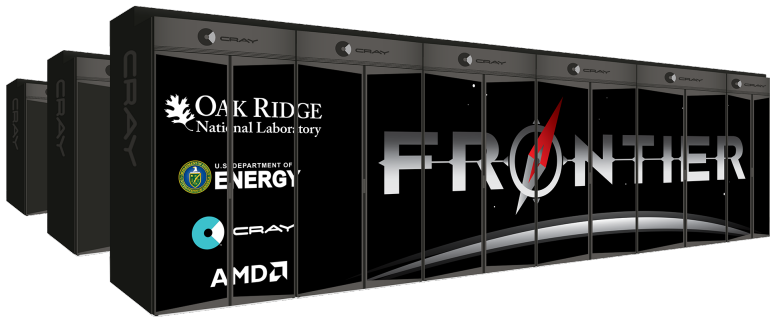
Conclusion



August Kamp and DALL-E, from *Girl with a Pearl Earring* by Johannes Vermeer



Source: <https://ourworldindata.org/>





Component (system-wide)	Failure Rate (over one year)	Failure Location (on/off node)
compute unit (soft error)	53.95%	on node
card	14.47%	off node
cable	8.55%	off node
link module	6.58%	off node
process/daemon	5.26%	off node
coolant monitor	4.61%	off node
other	6.58%	N/A

Source: *Failure Analysis and Quantification for Contemporary and Future Supercomputers* by Tan and DeBardeleben

Soft errors are prevalent due to:

- ▶ Component count
- ▶ Feature size vulnerability
- ▶ Energy savings through sub-threshold voltage
- ▶ Cost of detection logic

The Astronomer, Johannes Vermeer, 1668



Deep Learning

Artificial Neural Networks

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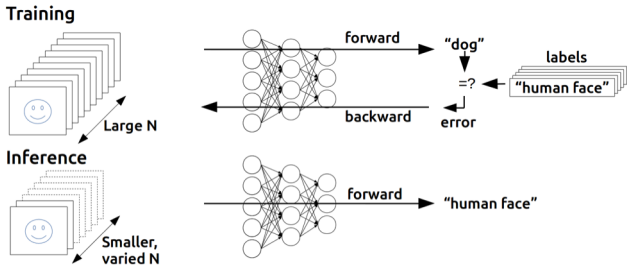
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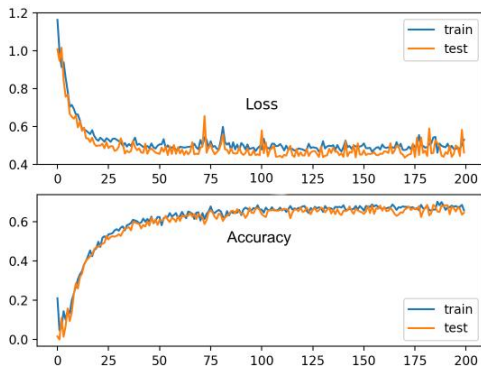
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Source: <https://developer.nvidia.com/>

Deep Learning Performance

Accuracy and loss metrics



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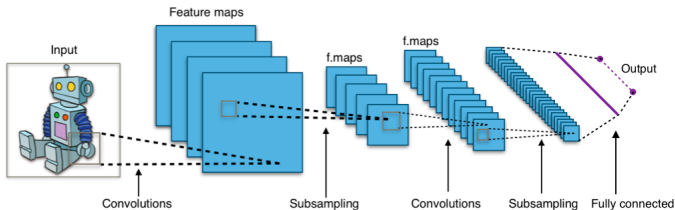
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Deep Learning Architecture

Many layers in specialized blocks



Typical structure of a convolutional neural network

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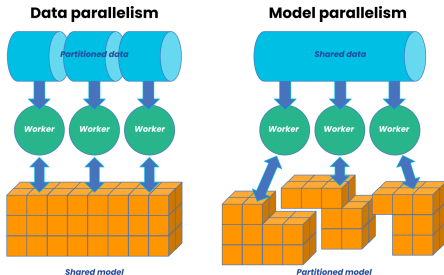
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Types of Distributed Deep Learning

Data parallel or model parallel



Source: <https://www.anyscale.com/>

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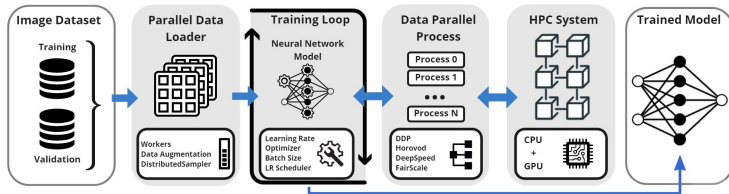
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Distributed Deep Learning Training

Mechanisms and tools



 PyTorch



deepspeed



FairScale

Elvis Rojas, Fabricio Quirós-Corella, Terry Jones, and Esteban Meneses. **Large-Scale Distributed Deep Learning: A Study of Mechanisms and Trade-Offs with PyTorch.** Latin America High Performance Computing Conference (CARLA), 2021, Guadalajara, Mexico.

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Tradeoffs in Distributed Learning

Faster execution and lower accuracy on Summit supercomputer

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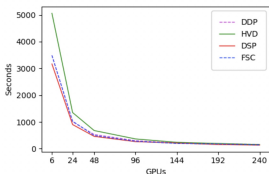
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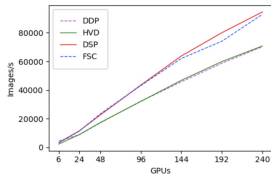
Experimental Setup

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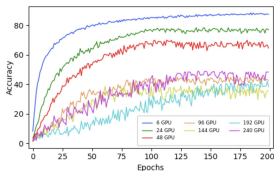
Conclusion



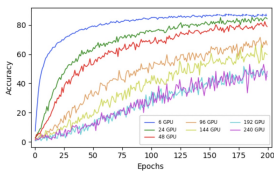
(a) Training time performance.



(b) Training throughput.



(a) DDP ResNet50.



(b) DDP ResNet101.

Hyperparameter Tuning

Crucial in bringing up performance

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Accuracy of DT mechanisms and DL models scaling on GPUs

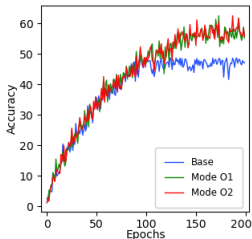
GPU	R50	LR	R101	LR	V16	LR	V19	LR	R50	LR	R101	LR	V16	LR	V19	LR
	DDP								HVD							
6	87/66	α	86/68	β	75/64	α	69/58	β	73/68	α	69/63	α	71/60	α	65/54	α
24	78/63	β	79/65	β	74/61	α	64/55	β	70/65	α	67/61	α	63/55	α	53/46	α
48	69/59	β	74/60	β	61/55	β	56/50	β	68/63	α	63/59	α	45/44	α	30/31	α
96	44/40	β	40/37	β	48/45	γ	52/45	γ	63/59	α	65/61	α	48/47	α	36/32	α
144	35/34	β	47/40	γ	46/45	γ	47/37	γ	61/56	α	68/61	α	42/40	α	40/36	α
192	38/37	β	55/50	γ	37/33	γ	27/26	γ	57/55	α	60/58	α	36/30	α	26/25	α
240	48/40	γ	48/40	γ	46/40	γ	35/27	γ	57/53	α	73/64	α	32/27	α	28/20	α
	DSP								FSC							
6	71/59	β	72/63	β	74/62	β	70/64	β	86/75	β	79/67	β	77/59	β	73/60	β
24	72/63	β	68/60	β	70/63	β	68/57	β	81/76	β	77/74	β	75/63	β	71/64	β
48	66/54	β	61/57	β	52/45	β	51/43	β	77/55	β	75/68	β	71/61	β	70/65	β
96	65/55	β	60/51	β	44/40	β	42/37	β	52/45	β	51/50	β	48/42	β	55/65	β
144	58/51	β	63/56	β	45/41	β	40/36	β	50/44	β	47/42	β	54/44	β	55/50	β
192	60/50	β	64/60	β	41/38	γ	39/37	γ	37/33	α	40/37	α	42/39	β	40/35	β
240	54/48	γ	52/45	γ	40/38	γ	33/31	γ	45/42	α	45/40	α	43/40	β	38/33	β

LR: $\alpha = 0.01$, $\beta = 0.001$, $\gamma = 0.0001$

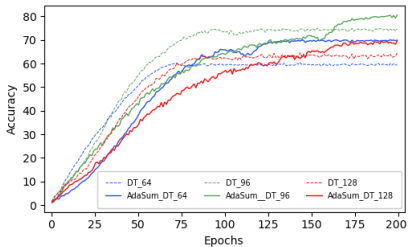
Parameters: learning rate, patience, batch size

Critical Optimizations

Significant impact on performance



Using mixed precision



Using optimizer

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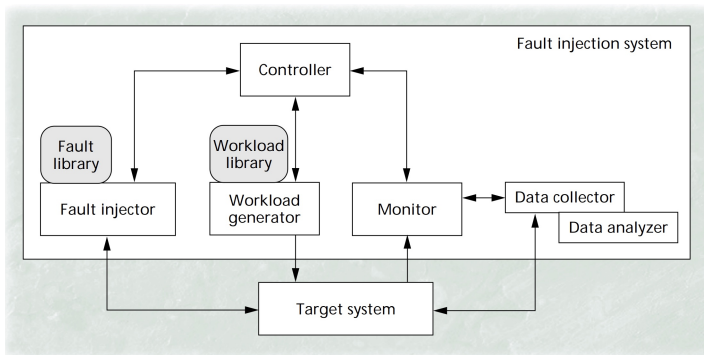
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Fault Injection

A first categorization



Source: *Fault Injection: Techniques and Tools* (Hsueh et al)

Types: dynamic (runtime) and static (compile time)

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Checkpointing

Dumping state of application

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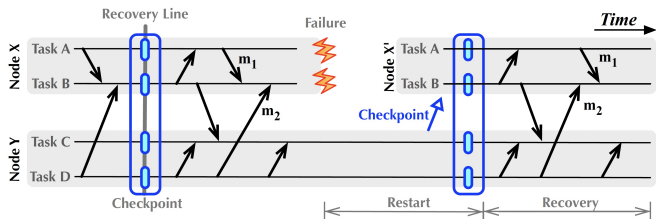
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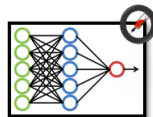
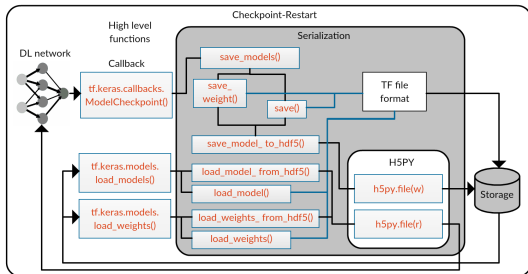
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Checkpoint Alteration

Using checkpoints to inject failures



- ▶ Disadvantage: does not capture entire spectrum of faults
- ▶ Advantages: controllable and portable

Elvis Rojas, Diego Pérez, Jon C. Calhoun, Leonardo Bautista Gomez, Terry Jones, Esteban Meneses. **Understanding Soft Error Sensitivity of Deep Learning Models and Frameworks through Checkpoint Alteration**. IEEE International Conference on Cluster Computing (CLUSTER), 2021, Portland, Oregon, United States.

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Failure Injector

Highly configurable

Setting	Description
<i>hdf5_file</i>	The path of the HDF5 file to corrupt
<i>injection_probability</i>	The probability that each injection attempt is successful
<i>injection_type</i>	Either "count" or "percentage"; the former allows an integer number of injection attempts, the latter allows a percentage of the file that can be corrupted
<i>injection_attempts</i>	The value for the <i>injection_type</i>
<i>float_precision</i>	16, 32, or 64 bit precision to use for each corruption of a floating-point number
<i>corruption_mode</i>	<ul style="list-style-type: none"><i>bit_mask</i>, A pattern of bits to flip (e.g., 101101), the first bit to apply the mask in each value is randomly selected from [0 to <i>float_precision</i> - length(<i>bit_mask</i>)], zeros are padded to both sides of the mask to match <i>float_precision</i>, then we XOR the mask against the floating-point value<i>bit_range</i>, [first_bit, last_bit] a range of corruptible bits from 0 to <i>float_precision</i> - 1<i>scaling_factor</i>, a scale factor to multiply each value
<i>allow_NaN_values</i>	If false, the corrupter does not transform a value to a NaN or INF
<i>locations_to_corrupt</i>	The list of locations to corrupt; all sublocations inside a location will be corrupted
<i>use_random_locations</i>	If true, it will ignore <i>locations_to_corrupt</i> and pick a random location every time

```
ckpt_tf_vgg_e_5.h5
├── model_weights
│   ├── block1_conv1
│   ├── block1_conv2
│   ├── block1_pool
│   ├── block2_conv1
│   ├── block2_conv2
│   ├── block2_pool
│   ├── block3_conv1
│   ├── block3_conv2
│   ├── block3_conv3
│   ├── block3_pool
│   ├── block4_conv1
│   ├── block4_conv2
│   ├── block4_conv3
│   ├── block4_pool
│   ├── block5_conv1
│   ├── block5_conv2
│   ├── block5_conv3
│   └── block5_pool
├── fc1
├── fc2
├── flatten
├── input_1
└── predictions
```

Works on HDF5 checkpoint files (Chainer, PyTorch, TensorFlow)

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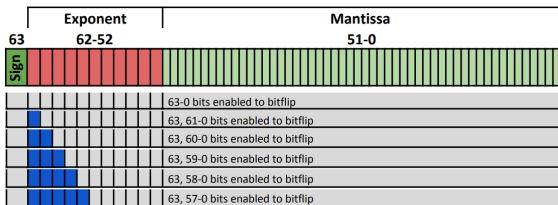
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IEEE-754 Sensitivity

Impact of bit flip on floating-point numbers



Incidence of NaN and extreme values (N-EV).

Bit-flips	Trainings	Chainer						PyTorch						TensorFlow					
		ResNet50		VGG16		AlexNet		ResNet50		VGG16		AlexNet		ResNet50		VGG16		AlexNet	
		N-EV	%	N-EV	%	N-EV	%	N-EV	%	N-EV	%	N-EV	%	N-EV	%	N-EV	%	N-EV	%
1	250	1	0.4	0	0	0	0	1	0.4	1	0.4	0	0	1	0.4	0	0	1	0.4
10	250	18	7.2	7	2.8	15	6	22	8.8	17	6.8	12	4.8	17	6.8	7	2.8	7	2.8
100	250	122	48.8	32	12.8	96	38.4	142	56.8	163	65.2	119	47.6	167	66.8	83	33.2	106	42.4
1000	250	249	99.6	188	75.2	241	96.4	249	99.6	248	99.2	249	99.6	246	98.4	227	90.8	234	93.6

Critical bit: most significant bit of the exponent

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Impact of Bitflips

Deep neural networks are quite resilient

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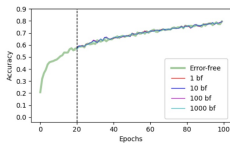
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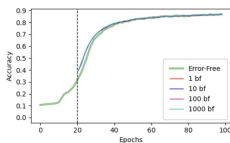
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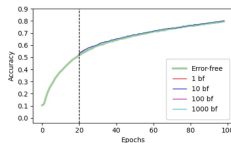
Conclusion



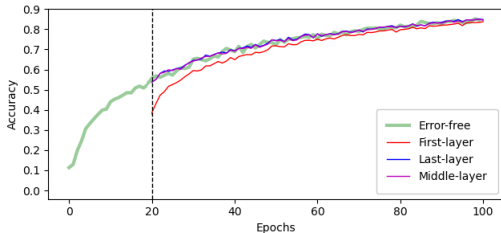
(a) Chainer with ResNet50.



(b) PyTorch with VGG16.



(c) TensorFlow with AlexNet.



Impact of Other Variables

Bit masks and floating-point precision

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Multi-bit mask applied to DL framework training.

Bits	Mask	Chainer		PyTorch		TensorFlow	
		AvgI-Acc	N-EV	AvgI-Acc	N-EV	AvgI-Acc	N-EV
0	00000000	57.6		30.01		39.2	
3	10001010	57.3	1	29.9	1	36.8	0
4	01101010	57.1	3	29.9	0	36.6	0
4	10110010	57.4	0	29.1	1	36.7	1
5	11110001	53	0	27.2	0	36.5	3
6	11101101	57.4	1	29.9	2	36.8	3

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Incidence of NaN and extreme values in 16 bit and 32 bit precision.

Bit-flips	DL Train	16 bits			32 bits		
		ResNet(%)	VGG(%)	AlexNet(%)	ResNet(%)	VGG(%)	AlexNet(%)
1	250	0.4	0	0.4	1.2	2.4	2.8
10	250	10.4	11.6	7.2	15.6	17.2	13.2
100	250	59.2	69.2	60	76.8	72.4	68
1,000	250	96	77.2	86	98	78	91.6

View of Delft, Johannes Vermeer, 1661

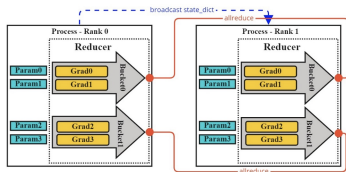


Distributed Deep Learning

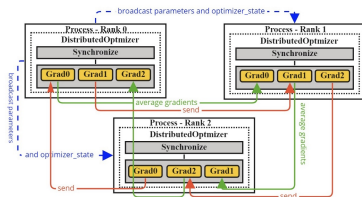
Implementations

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Distributed training process in DDP.



Distributed training process in HVD.

Elvis Rojas, Diego Pérez, Esteban Meneses. **Exploring the Effects of Silent Data Corruption in Distributed Deep Learning Training.** International Symposium on Computer Architecture and High Performance Computing (SBAC-PAD), 2022, Bordeaux, France.

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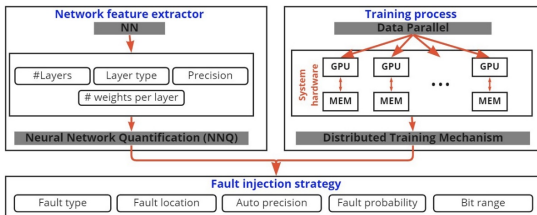
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Failure Injection

Adapted to a distributed environment



Failure injection strategy

Effects of a single bit-flip on distributed training

CNN	DT Mech.	Structure	#BF (Bit-Af)	# Processes	# Trainings	RWC	RWC %
ResNet	DDP	Optimizer	1 (Any)	1/8	180	85	47.2
		Model	1 (Any)	1/8	180	109	60.5
	HVD	Optimizer	1 (Any)	1/8	180	76	42.2
		Model	1 (Any)	1/8	180	103	57.2
VGG	DDP	Optimizer	1 (Any)	1/8	180	82	45.5
		Model	1 (Any)	1/8	180	101	56.1
	HVD	Optimizer	1 (Any)	1/8	180	80	44.4
		Model	1 (Any)	1/8	180	127	70.5

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Sensitivity of
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Injection Impact

Measured on model and optimizer

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Effects of multiple bit-flips on distributed training

		Model							
		DDP				HVD			
		1	2	3	4	5	6	7	8
#BF (Bit-Af)	# Proc/TProc	ACC	STD	CV	NaN	ACC	STD	CV	NaN
1 (Any)	4/8	71.102	0.299	0.004	1	69.814	0.123	0.002	1
1 (Any)	8/8	71.073	0.391	0.006	1	69.871	0.099	0.001	0
10 (Any)	1/8	71.128	0.457	0.006	4	69.746	0.077	0.001	4
10 (Any)	4/8	71.202	0.321	0.005	8	69.813	0.139	0.002	3
10 (Any)	8/8	71.272	0.385	0.005	8	69.749	0.14	0.002	2
100 (Any)	1/8	70.992	0.453	0.006	16	69.774	0.223	0.003	16
100 (Any)	4/8	-	-	-	18	69.766	0.183	0.003	14
100 (Any)	8/8	-	-	-	18	69.771	0.104	0.001	12

		Optimizer											
		DDP						HVD					
		9	10	11	12	13	14	15	16	17	18	19	20
#BF (Bit-Af)	# Proc/TProc	ACC	STD	CV	NaN	AccR	TF	ACC	STD	CV	NaN	AccR	TF
1 (Any)	4/8	71.217	0.335	0.005	-	-	-	69.772	0.111	0.002	-	-	-
1 (Any)	8/8	71.044	0.586	0.008	-	-	-	69.768	0.089	0.001	-	-	-
10 (Any)	1/8	70.705	1.596	0.023	1	1	1	69.757	0.273	0.004	-	-	2
10 (Any)	4/8	70.596	1.913	0.027	2	-	-	69.768	0.152	0.002	-	-	-
10 (Any)	8/8	69.043	2.125	0.031	4	3	-	69.82	0.12	0.002	1	-	-
100 (Any)	1/8	66.776	5.596	0.084	5	5	3	69.048	1.256	0.018	5	2	3
100 (Any)	4/8	58.17	-	-	16	1	1	69.774	0.079	0.001	7	-	5
100 (Any)	8/8	-	-	-	17	-	1	68.728	1.792	0.026	6	3	3

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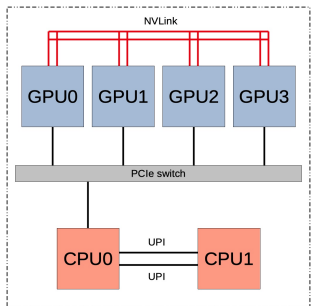
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Performance Analysis

Studying sensitivity to noise



Supercomputing node

(source: <https://hpcf.umbc.edu/>)



Juwels Supercomputer

Elvis Rojas, Michael Knobloch, Nour Daoud, Esteban Meneses, Bernd Mohr. **Early Experiences of Noise-Sensitivity Performance Analysis of a Distributed Deep Learning Framework.** HPC for International Collaboration between Europe and Latin America Workshop, IEEE Cluster, 2022, Heidelberg, Germany.

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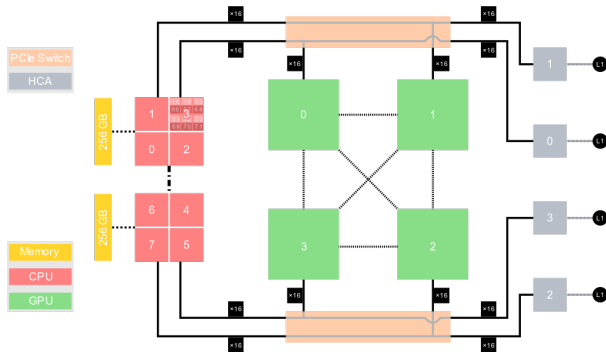
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Architecture of computational node in Juwels-Booster

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Sensitivity and Coexistence

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PhD

PERFORMANCE OF DL TRAINING (EXECUTION TIME IN SECONDS) IN
SINGLE NODE SHARED AND EXCLUSIVE NUMA ENVIRONMENTS.

Repetition	Exclusive NUMA Domains		Shared NUMA Domains	
	No Noise	With Noise	No Noise	With Noise
MIN	134.22	134.83	143.31	190.37
Average time	135.77	138.20	145.62	256.27
Standard Dev.	1.377	2.97	1.45	39.26

SUMMARY OF THE PERFORMANCE OF DL TRAINING (EXECUTION TIME IN
SECONDS) IN TWO NODE SHARED AND EXCLUSIVE NUMA
ENVIRONMENTS.

Repetition	Exclusive NUMA Domain		Shared NUMA Domain	
	No Noise	With Noise	No Noise	With Noise
MIN	81.13	77.92	83.44	213.86
Average time	81.81	81.05	85.58	231.21
Standard Dev.	1.54	1.45	1.36	23.50

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Concluding Remarks

- ▶ Strong convergence of HPC, AI, and data science
- ▶ Checkpoint alteration is a controllable, portable and scalable fault injection approach
- ▶ Deep learning resilient to soft errors, albeit there is a critical bit
- ▶ Distributed deep learning can coexist with other complementary executions

Thank you!

emeneses@cenat.ac.cr



A supercomputer painted by Johannes Vermeer

(Daniel Amador and DALL-E)